

# ECE 306L - DIGITAL FILTERS - LAB 8

## SIMPLE NONRECURSIVE DIGITAL FILTERS

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### OBJECTIVE

The objective of this lab is to use Simulink to obtain the frequency responses of some simple nonrecursive digital filters.

### PRELAB

1. Given the following 1st order nonrecursive digital filter with difference equation

$$y[n] = x[n] + x[n - 1]$$

- a. Find  $H(z) = \frac{Y(z)}{X(z)}$
- b. Find the poles and zeroes
- c. Sketch the pole-zero diagram
- d. How are the locations of the poles of recursive difference equations different from those of nonrecursive difference equations
- e. Make use of the pole-zero diagram in part (b) to sketch the frequency response for  $-\frac{f_s}{2} \leq f \leq \frac{f_s}{2}$  when  $f_s = 10^4$  samples/sec
- f. Is this filter lowpass, highpass or bandpass. How can you tell
- g. Find the frequency response

$$H(e^{j2\pi f/f_s}) = H(z)|_{z=e^{j2\pi f/f_s}}$$

- h. Use  $H(e^{j2\pi f/f_s})$  to obtain an equation for the sinusoidal steady state response  $y[n]$  when  $x(t) = 5\cos(2000t)$  sampled at  $f_s = 10^4$  samples/sec
- i. Use Matlab to obtain a full graph of the magnitude of the frequency response as follows

$$\left| H(e^{j2\pi f/f_s}) \right| \text{ for } -\frac{f_s}{2} \leq f \leq \frac{f_s}{2}$$

for  $f_s = 10^4$  samples/sec

- j. Verify that your results in parts (e) and (i) are the same
  - k. Draw a Simulink block diagram for realizing the difference equation for when  $x[n]$  is a sinusoid
2. Given a 7th order nonrecursive digital filter with the following zeros

$$z = \frac{1}{\sqrt{2}} \pm j\frac{1}{\sqrt{2}} \quad z = \pm j \quad z = -\frac{1}{\sqrt{2}} \pm j\frac{1}{\sqrt{2}} \quad z = -1$$

- a. Find the transfer function  $H(z)$
- b. Sketch the pole-zero diagram
- c. Make use of the pole-zero diagram to sketch the frequency response for  $-\frac{f_s}{2} \leq f \leq \frac{f_s}{2}$  when  $f_s = 10^4$  samples/sec
- d. Is this filter lowpass, highpass or bandpass. How can you tell
- e. Find the frequency response  $H(e^{j2\pi f/f_s})$

- f. Find the value of  $b_o$  so that the gain is equal to one when  $f = 0$
- g. Use  $H(e^{j2\pi f/f_s})$  from part (f) to obtain an equation for the sinusoidal steady state response  $y[n]$  when  $x(t) = 5\cos(2000t)$  sampled at  $f_s = 10^4$  samples/sec
- h. Use Matlab to obtain a full page graph of the magnitude of the frequency response from part (f) as follows

$$\left| H(e^{j2\pi f/f_s}) \right| \quad \text{for} \quad -f_s/2 \leq f \leq f_s/2$$

- i. Verify that your results in parts (c) and (h) are the same
- j. Find the difference equation for this digital filter
- k. Draw a Simulink block diagram for realizing the difference equation for  $y[n]$  when  $x[n]$  is a sinusoid
3. Repeat Problem (2) for the 7th order nonrecursive digital filter with zeroes

$$z = \frac{1}{\sqrt{2}} \pm j \frac{1}{\sqrt{2}} \quad z = \pm j \quad z = -\frac{1}{\sqrt{2}} \pm j \frac{1}{\sqrt{2}} \quad z = 1$$

Find the value of  $b_o$  so that the gain is equal to one when  $f = f_s/2$

4. Repeat Problem (2) for the 6th order nonrecursive digital filter with zeroes

$$z = \frac{1}{\sqrt{2}} \pm j \frac{1}{\sqrt{2}} \quad z = -\frac{1}{\sqrt{2}} \pm j \frac{1}{\sqrt{2}} \quad z = \pm 1$$

Find the value of  $b_o$  so that the gain is equal to one when  $f = f_s/4$

## LAB

1. For the difference equation from Problem (1) as follows

$$y[n] = x[n] + x[n-1]$$

with  $f_s = 10^4$  samples/sec

- a. Use Simulink to obtain the sinusoidal steady state responses at ten representative frequencies. Make at least three screen captures at low, medium and high frequencies
- b. Use your Simulink results to calculate  $\left| H(e^{j2\pi f/f_s}) \right|$  for each of your sinusoids
- c. Put your values of  $\left| H(e^{j2\pi f/f_s}) \right|$  on your Matlab graph from the prelab
2. For the digital filter of Problem (2) with  $f_s = 10^4$  samples/sec
- a. Use Simulink to obtain the sinusoidal steady state responses at ten representative frequencies. Put the outputs of your digital filter through an analog lowpass filter to obtain the corresponding sinusoids  $y(t)$ . Make screen captures that include low, medium and high frequencies
- b. Use your Simulink results to calculate  $\left| H(e^{j2\pi f/f_s}) \right|$  for each of your sinusoids
- c. Put your values of  $\left| H(e^{j2\pi f/f_s}) \right|$  on your Matlab graph from the prelab

3. For the digital filter of Problem (3) with  $f_s = 10^4$  samples/sec
  - a. Use Simulink to obtain the sinusoidal steady state responses at ten representative frequencies. Put the outputs of your digital filter through an analog lowpass filter to obtain the corresponding sinusoids  $y(t)$ . Make screen captures that include low, medium and high frequencies
  - b. Use your Simulink results to calculate  $\left| H\left(e^{j2\pi f/f_s}\right) \right|$  for each of your sinusoids
  - c. Put your values of  $\left| H\left(e^{j2\pi f/f_s}\right) \right|$  on your Matlab graph from the prelab
  
4. For the digital filter of Problem (4) with  $f_s = 10^4$  samples/sec
  - a. Use Simulink to obtain the sinusoidal steady state responses at ten representative frequencies. Put the outputs of your digital filter through an analog lowpass filter to obtain the corresponding sinusoids  $y(t)$ . Make screen captures that include low, medium and high frequencies
  - b. Use your Simulink results to calculate  $\left| H\left(e^{j2\pi f/f_s}\right) \right|$  for each of your sinusoids
  - c. Put your values of  $\left| H\left(e^{j2\pi f/f_s}\right) \right|$  on your Matlab graph from the prelab

## POSTLAB

1. Compare your Matlab and Simulink results for  $\left| H\left(e^{j2\pi f/f_s}\right) \right|$  for each of the four filters
2. Why are the orders of nonrecursive digital filters higher than the orders of recursive digital filters that meet the same frequency spec