

ECE 306L - DIGITAL FILTERS - LAB 6

SIMPLE RECURSIVE DIGITAL FILTERS

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OBJECTIVE

The objective of this lab is to use Simulink to obtain the frequency responses of some simple recursive digital filters.

PRELAB

1. Given a recursive digital filter with the following difference equation

$$y[n] = 0.9y[n - 1] + 0.05x[n] + 0.05x[n - 1]$$

- Find $H(z) = \frac{Y(z)}{X(z)}$
- Find the frequency response

$$H(e^{j2\pi f/f_s}) = H(z)|_{z=e^{j2\pi f/f_s}}$$

- Use $H(e^{j2\pi f/f_s})$ to obtain an equation for the sinusoidal steady state response $y[n]$ when $x(t) = 5\cos(2000t)$ is sampled at $f_s = 10^4$ samples/sec
- Use Matlab to calculate $|H(e^{j2\pi f/f_s})|$ at ten representative frequencies for when $f_s = 10^4$ samples/sec
- Use Matlab to obtain a full page plot of the magnitude of the frequency response as follows

$$|H(e^{j2\pi f/f_s})| \text{ for } -f_s/2 \leq f \leq f_s/2$$

for $f_s = 10^4$ samples/sec

- Verify that your calculations in part (d) agree with your graph in part (e)
 - Is this filter lowpass, highpass or bandpass. How can you tell
 - Draw a Simulink block diagram of delays, multipliers and adders for realizing the difference equation for when $x[n]$ is a sinusoid
2. Given a digital filter with the following transfer function

$$H(z) = \frac{Y(z)}{X(z)} = b_0 \frac{z - 1}{z + 0.9}$$

- Find the frequency response

$$H(e^{j2\pi f/f_s}) = H(z)|_{z=e^{j2\pi f/f_s}}$$

- Find b_0 so the gain $H(e^{j2\pi f/f_s})$ is equal to one when $f = f_s/2$
- Use $H(e^{j2\pi f/f_s})$ to obtain an equation for the sinusoidal steady state response $y[n]$ when $x(t) = 5\cos(2000t)$ sampled at $f_s = 10^4$ samples/sec

- d. Use Matlab to calculate $\left|H\left(e^{j2\pi f/f_s}\right)\right|$ at ten representative frequencies for when $f_s = 10^4$ samples/sec
- e. Use Matlab to obtain a full page plot of the magnitude of the frequency response as follows

$$\left|H\left(e^{j2\pi f/f_s}\right)\right| \text{ for } -f_s/2 \leq f \leq f_s/2$$

for $f_s = 10^4$ samples/sec

- f. Verify that your calculations in part (d) agree with your graph in part (e)
- g. Is this filter lowpass, highpass or bandpass. How can you tell
- h. Find the difference equation for this filter
- i. Draw a Simulink block diagram of delays, multipliers and adders for realizing the difference equation for when $x[n]$ is a sinusoid
3. Given a digital filter with the following transfer function

$$H(z) = \frac{Y(z)}{X(z)} = b_0 \frac{(z+1)(z-1)}{(z+j0.9)(z-j0.9)}$$

- a. Find the frequency response

$$H\left(e^{j2\pi f/f_s}\right) = H(z)\Big|_{z=e^{j2\pi f/f_s}}$$

- b. Find b_0 so the gain is equal to one when $f = f_s/4$
- c. Use $H\left(e^{j2\pi f/f_s}\right)$ to obtain an equation for the sinusoidal steady state response $y[n]$ when $x(t) = 5\cos(2000t)$ sampled at $f_s = 10^4$ samples/sec
- d. Use Matlab to calculate $\left|H\left(e^{j2\pi f/f_s}\right)\right|$ at ten representative frequencies for when $f_s = 10^4$ samples/sec
- e. Use Matlab to obtain a full page plot of the magnitude of the frequency response as follows

$$\left|H\left(e^{j2\pi f/f_s}\right)\right| \text{ for } -f_s/2 \leq f \leq f_s/2$$

for $f_s = 10^4$ samples/sec

- f. Verify that your calculations in part (d) agree with your graph in part (e)
- g. Is this filter lowpass, highpass or bandpass. How can you tell
- h. Find the difference equation for this filter
- i. Draw a Simulink block diagram of delays, multipliers and adders for realizing the difference equation for $y[n]$ when $x[n]$ is a sinusoid

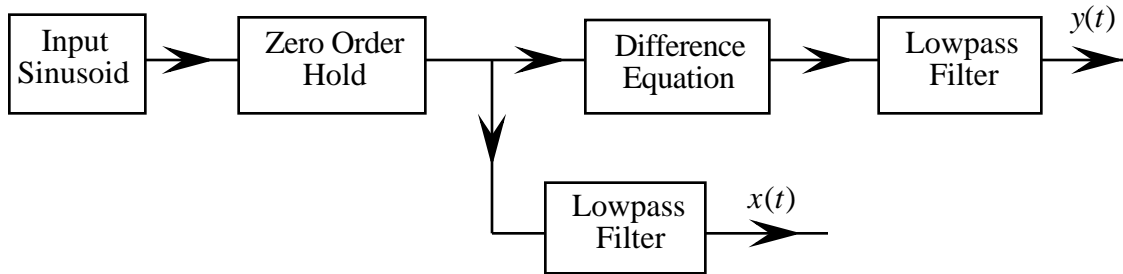
LAB

1. For the difference equation of Problem (1) as follows

$$y[n] = 0.9y[n-1] + 0.05x[n] + 0.05x[n-1]$$

with $f_s = 10^4$ samples/sec

- a. Use Simulink to obtain the sinusoidal steady state responses at the frequencies you chose in Prelab Problem (1d). Put both $x_{SIH}(t)$ and $y_{SIH}(t)$ through lowpass analog filters as follows



to obtain the sinusoids for calculating the gains in part (b) below. Make screen captures at low, medium and high frequencies of both $x(t)$ and $y(t)$. Be sure to set the sample time of the zero order hold

- b. Use your Simulink results to calculate $\left|H\left(e^{j2\pi f/f_s}\right)\right|$ for each of your sinusoids. Put your results in a Table
- c. Put your values of $\left|H\left(e^{j2\pi f/f_s}\right)\right|$ on your Matlab graph from the prelab
2. For the difference equation of Problem (2) with $f_s = 10^4$ samples/sec
- a. Use Simulink to obtain the sinusoidal steady state responses at the frequencies you chose in Prelab Problem (2d). Put both $x_{SIH}(t)$ and $y_{SIH}(t)$ through analog lowpass filters to obtain the corresponding sinusoids. Make screen captures at low, medium and high frequencies
- b. Use your Simulink results to calculate $\left|H\left(e^{j2\pi f/f_s}\right)\right|$ for each of your sinusoids. Put your results in a Table
- c. Put your values of $\left|H\left(e^{j2\pi f/f_s}\right)\right|$ on your Matlab graph from the prelab
3. For the difference equation of Problem (3) with $f_s = 10^4$ samples/sec
- a. Use Simulink to obtain the sinusoidal steady state responses at the frequencies you chose in Prelab Problem (3d). Put both $x_{SIH}(t)$ and $y_{SIH}(t)$ through analog lowpass filters to obtain the corresponding sinusoids. Make screen captures at low, medium and high frequencies
- b. Use your Simulink results to calculate $\left|H\left(e^{j2\pi f/f_s}\right)\right|$ for each of your sinusoids. Put your results in a Table
- c. Put your values of $\left|H\left(e^{j2\pi f/f_s}\right)\right|$ on your Matlab graph from the prelab

POSTLAB

1. Compare your Matlab and Simulink results for $\left|H\left(e^{j2\pi f/f_s}\right)\right|$ for each of the three filters
2. Given the following two sinusoids

$$x_1(t) = 5\cos(2\pi ft) \quad \text{and} \quad x_2(t) = 5\cos(2\pi(f + f_s)t)$$

- a. Describe how $x_1(t)$ and $x_2(t)$ are related
 - b. Show that the samples of $x_1(t)$ and $x_2(t)$ are the same with $x_1[n] = x_2[n]$
3. Make use of Problem (2) to explain why $\left|H\left(e^{j2\pi f f_s}\right)\right|$ is periodic with period f_s
4. Sketch the frequency response $\left|H\left(e^{j2\pi f f_s}\right)\right|$ for each of the following filters for $-2f_s \leq f \leq 2f_s$
- a. Lowpass
 - b. Highpass
 - c. Bandpass